

Engineering Tool for MP2000 Series Machine Controller

MPE720 Version 6

USER'S MANUAL

New Features of Version 6.04



YASKAWA

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Chapter 1

Motion Command Assist Function

This chapter describes the "motion command assist function".

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1.1.1 Insert the Motion Command	1-2
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1.1 Motion Command Assist Function

The Motion Command Assist Function helps to input motion instructions when creating the motion program.

The motion program is described with a text-type Motion Language. Motion instructions should be input complying with their own format.

Using the Motion Command Dialog Box, motion instructions will be easier to input.

1.1.1 Insert the Motion Command

Right-click the mouse in the motion program editor. The pop-up menu will appear. The motion instructions can be selected and inserted from the pop-up menu. There are two methods to access the Motion Command Assist Function.

- Select “Motion command assist...” from the pop-up menu :

The Motion Command Assist Dialog Box is displayed. Select an instruction from the "command" column.

- Select “Insert motion command” – “Instruction” from the pop-up menu :

The Motion Command Assist Dialog Box is displayed. Select a motion instruction from the pop-up menu and it is displayed in the "command" column.

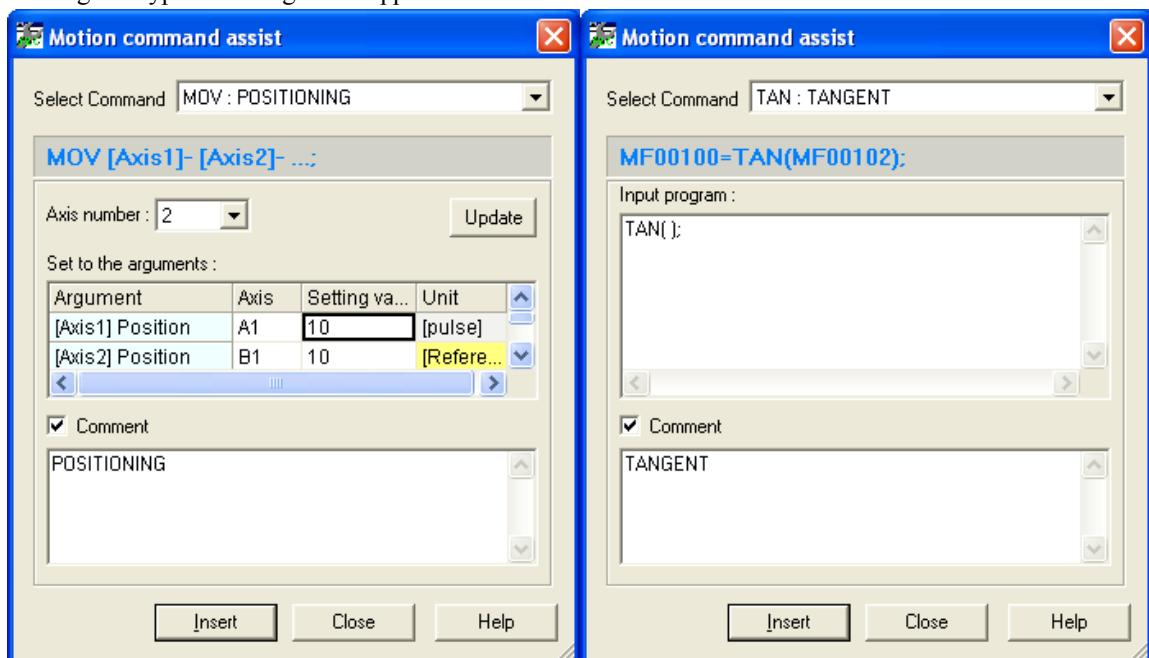
(1) Input Motion Instruction

1. Right-click the mouse in the motion program editor and select “Insert motion command” from the pop-up menu.

The Motion Command Assist Dialog Box is displayed.

2. Complete all settings and click the Insert button.

The following two types of dialog boxes appear.



Select Command (Select Command **MOV : POSITIONING**)

When clicking **▼**, the instructions which can be inserted are displayed. Select the instruction to be inserted.

Motion instruction Format (**MOV [Axis1]- [Axis2]- ...**)

The format of the selected instruction is displayed.

Number of Axes (**2**)

Set the number of controlled axes. When the number of axes of selected instruction is a fixed number, the fixed number is displayed automatically and shown in gray.

Refresh ()

Click the button to update the Motion Command Assist Dialog Box.

Setting the arguments ()

Argument	Axis	Setting va...	Unit
[Axis1] Position	A1	10	[pulse]
[Axis2] Position	B1	10	[Referenc...

The arguments of each motion instruction are displayed. Set the "axis name" and the "setting value" in the table.

Arguments: The argument names are displayed.

Axis: Set the logical axis name which is defined in the "group definition".

Setting value: The constant and the register number can be input. If the setting value can be omitted, "Optional" is displayed as default.

Unit: The unit of each argument is displayed.

When the units are not set, **[Reference Unit]** is displayed. The tool tip help is displayed when the mouse pointer is held over the unit. Set the unit according to the instruction.

Program code ()

```
TAN( );
```

This program code is displayed when the motion instruction does not need the "axis name" and "setting value".

Comment ()

Comment column ()

If "Comment" is selected, it is possible to add and edit comments in the "Comment column" for each instruction. If not, "Comment column" is shown in gray.

Insert ()

Click the button to insert the instruction.

Close ()

Click the button to close the Motion Command Assist Dialog Box.

Help ()

Click the button to display the "Machine Controller MP2200/MP2300 Motion Module User's Manual".

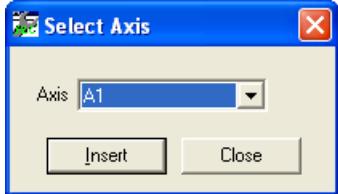
1.1.2 Insert Servo Enable, Servo Disable, Alarm Clear Instruction

The Servo Enable, Servo Disable, and Alarm Clear instruction can be easily inserted without considering the motion register.

1. Right-click the mouse in the motion program editor. Then select “Insert Motion Command” – “Servo Enable”, “Servo Disable” or “Alarm Clear” from the pop-up menu.

The Axis Dialog Box is displayed.

2. Select logical axis name from the Axis combo box. Then click the Insert button.



3. The instruction (Servo Enable, Servo Disable or Alarm Clear) is inserted at the cursor position.

Chapter 2

System Sub-window

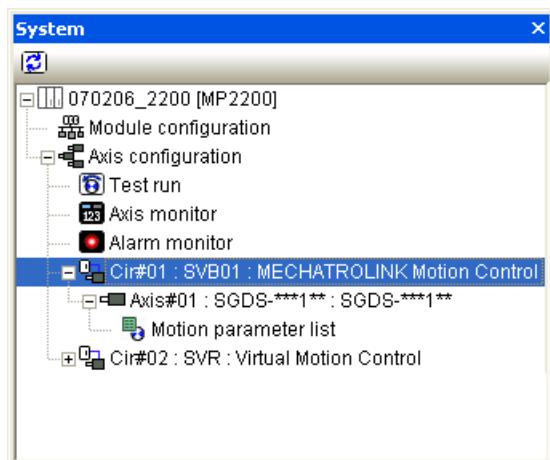
This chapter describes the System Sub-window.

2.1 System Sub-window	2-2
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2.1 System Sub-window

The System Sub-window manages the following functions.

- Module configuration
- Axis configuration
 - Test Run
 - Axis Monitor
 - Alarm Monitor
 - Motion Parameter List



Chapter 3

Test Run

This chapter describes how to use the Test Run function.

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3.1 Test Run

The Test Run function is for checking if the machine controller can operate an axis. It has three functions.

- Servo Enable, Servo Disable: Enable or Disable the specified axis.
- JOG: Jogs the specified axis with specified speed and direction.
- STEP: Runs the specified axis a specified distance.

The following two functions are implemented for monitoring.

- Axis Monitor: Monitors the status of each axis.
- Alarm Monitor: Monitors the "Alarm information" of all axes in one screen.

- ◆ The Test Run function can be operated when the target axis has the following status.

Axis		Motion Controller Operation Ready	Servo Ready	Motion Command Response Code
SVB built-in CPU	Servo	ON	ON	NOP
	Inverter	-	ON	NOP
SVA-01		ON	ON	NOP
SVR		ON	-	NOP
PO-01		ON	-	NOP



The Test Run function may not work correctly when a motion program or sequence program operates the axis.

3.1.1 Test Run Procedure

1. Double-click the Test Run Folder in the System Sub-window.

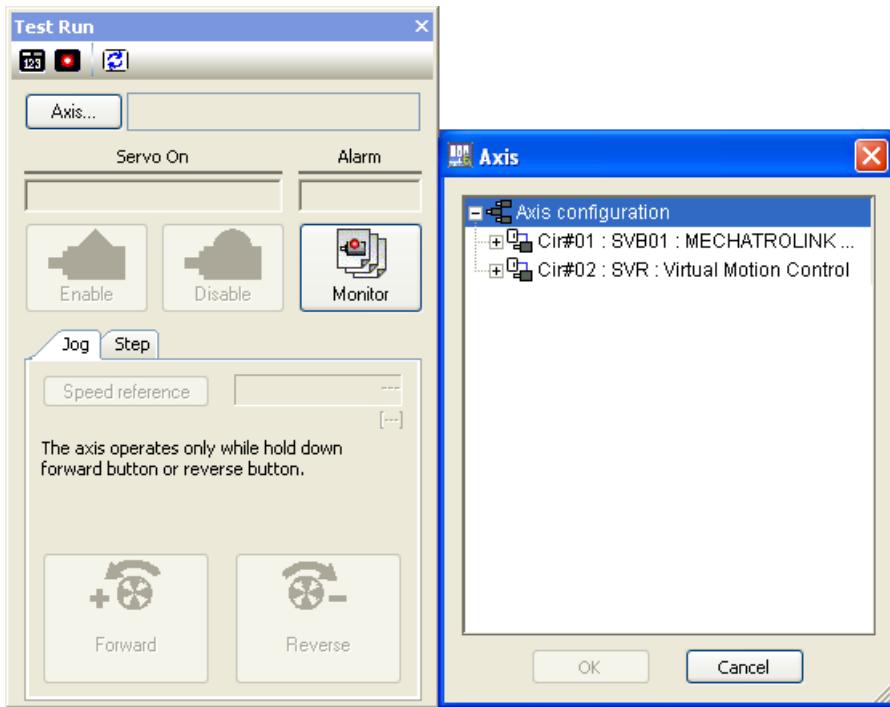
A Test Run warning window will be displayed.

2. Confirm the contents. Then click the Agree button.

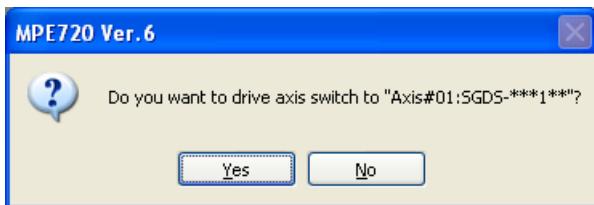


The Test Run Window and Axis Dialog Box is displayed.

3. Select the target axis from the Axis Dialog Box. Then click the OK button.



The following message is displayed.



4. The selected Axis name is displayed in the right side of the "Axis..." button when clicking the "Yes" button.

- ◆ The Test Run function can operate only one axis at a time.



Axis monitor ()

The Axis Monitor Window is displayed in the Main Window.

Alarm monitor ()

The Alarm Monitor Window is displayed in the Main Window.

Update ()

Updates the display of the Test Run Window.

Axis ()

The Axis Dialog Box is displayed.

Status ()

The status of the axis is displayed.

Enable ()

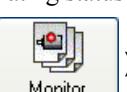
Click the button to enable the axis.

Disable ()

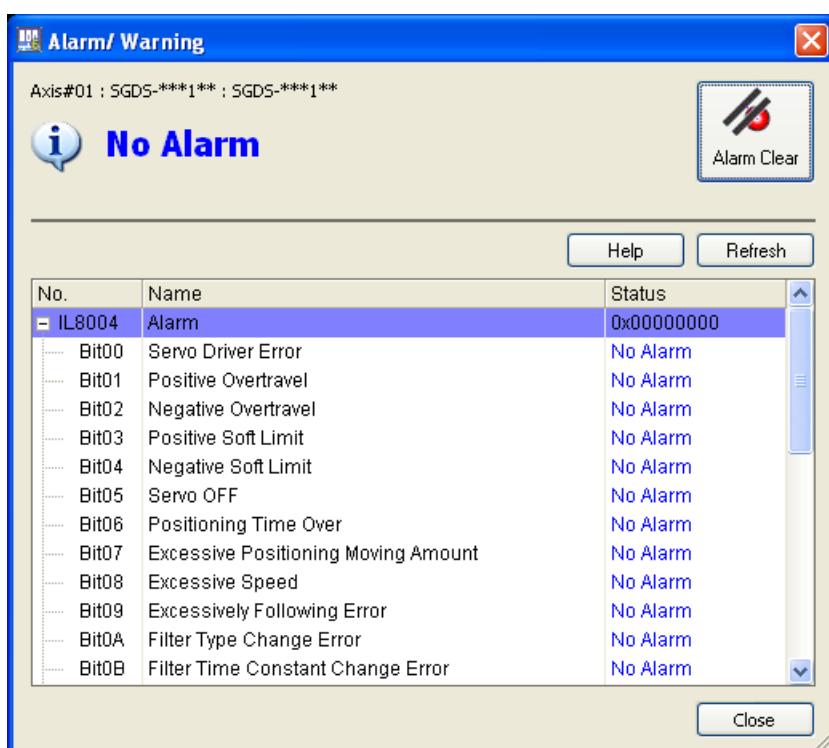
Click the button to disable the axis.

Monitor Status ()

The operating status of the monitor will be displayed.

Monitor ()

The Alarm Warning Dialog Box is displayed.



3.2 Servo Enable, Servo Disable

The axis can be enabled and disabled with this function. The status of the axis can also be monitored in the Test Run Dialog Box.

The way to operate and monitor the axis is described below.

3.2.1 Servo Enable

Enabling the axis and monitoring the status.

1. Click the Enable button.

The axis is enabled.

Axis status is changed to "Enabled".

The operation of Jog and Step becomes available.

3.2.2 Servo Disable

Disabling the axis and monitoring the status.

1. Click the Disable button.

The axis is disabled.

The status is changed to "Disabled".

Jog and Step cannot be used.

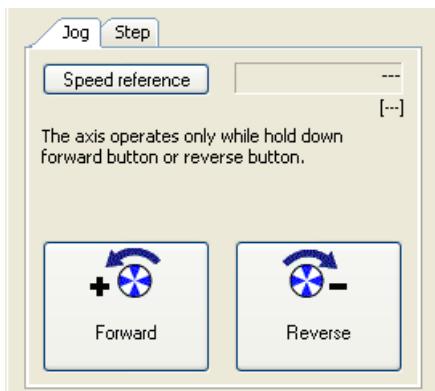
3.3 Jog Operation

The Jog operation is a function to run the forward or reverse direction of the axis. The running speed can be set in the Speed reference Dialog Box.



Jog is available only while the axis is enabled.

The axis will run while the Forward or Reverse button is pressed. The axis will stop when the Forward or Reverse button is released.



Speed reference (Speed reference)

The Speed reference Dialog Box is displayed, and the running speed (speed reference) is set in the dialog box.



The axis runs forward.

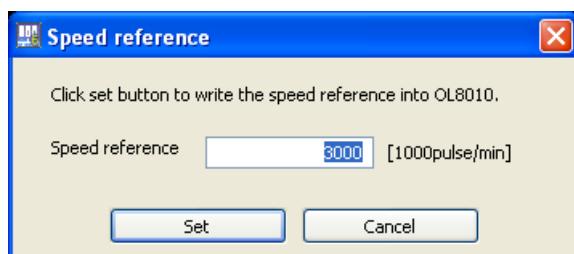


The axis runs reverse.

(1) Set the speed reference

1. Click the Speed reference button.

Speed reference Dialog Box is displayed.



2. Input speed reference. Then click the Set button.

- ◆ When the unit is not set, the following dialog box is displayed. Click the Open button to set the unit.



3.3.1 Jog Forward

The axis runs forward while the button is held down.

1. Hold down the Forward button with the mouse.

The axis runs forward.

2. Release the button.

The axis stops.

3.3.2 Jog Reverse

The axis runs reverse while the button is held down.

1. Hold down the Reverse button with the mouse.

The axis runs reverse.

2. Release the button.

The axis stops.

3.4 Step Operation

The step operation moves the axis a specified distance and then stops.

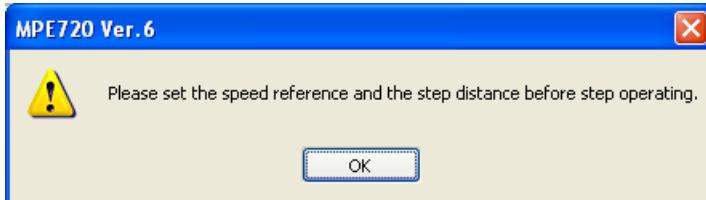
The axis starts moving when the Run button is clicked. Motion can be aborted with the Stop button.

The step operation can also repeat round trip motion several times.

The step operation operates under the following conditions.

- Servo is enabled.
- The speed reference and step distance must be set.

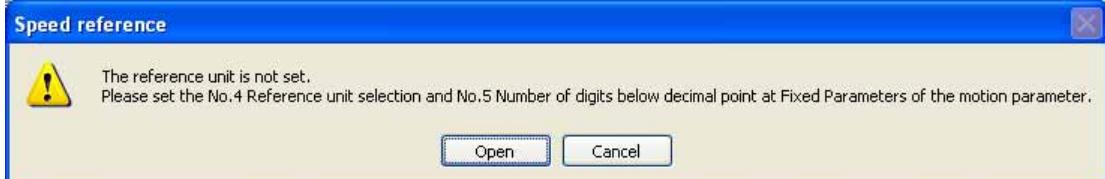
The "---" is displayed by default. If the Forward Reverse button is operated before setting them, the following error message is displayed.



- The unit for speed reference and step distance must be set.

The unit of speed reference and step distance is related to some fixed parameters. If changing the unit of one, the unit of the other is also changed.

The following error message is displayed if the unit is not set. To set the unit, click the Open button.



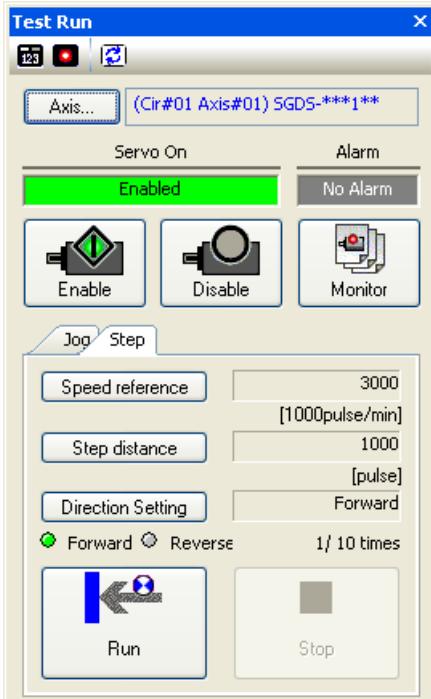
3.4.1 Step Operation Procedure

Please refer to "3.2 Servo Enable, Servo" to learn how to enable or disable servo.

1. Click the "Step" Tab.

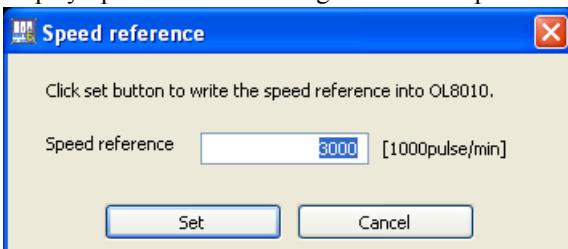
The Step Setting Dialog Box is displayed.

2. Click the "Speed reference", "Step distance" and "Direction setting" button and set them.



Speed reference (Speed reference)

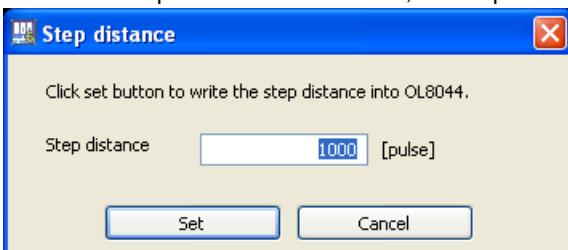
Display Speed reference Dialog Box and set speed reference.



Step distance (Step distance)

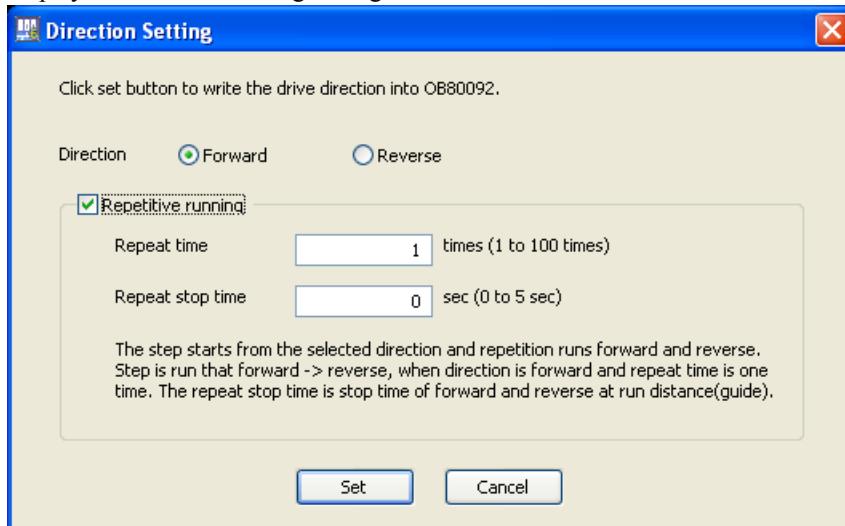
Display the Step distance Dialog Box and set the step distance.

- ◆ When the Step distance unit is not set, a fixed parameter of the Motion module is automatically read.



Direction setting ()

Display the Direction Setting Dialog Box and set the direction.



Direction: Set the direction for first motion.

Repetitive running: Check it for repeat operation.

Repeat time: Set the number of times to repeat.

i.e. Repeat time is 2.

Forward -> Reverse -> Forward -> Reverse.

Repeat stop time: Set the interval time between motion.

Forward Reverse ( Forward/  Forward,  Reverse/  Reverse)

"  " shows the direction of motor.

Repeat time (1/ 10 times)

"Current repeat time/ Setting repeat time" is displayed.



To start the step operation.



To stop the step operation. The following message is displayed when stopped.



3. Click the Run button.

The step operation starts.

Chapter 4

Axis Monitor

This chapter describes how to use the Axis Monitor.

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4.2 Axis Monitor Display	4-3
4.2.1 Toolbar	4-3
4.2.2 Circuit and Axis Display	4-3
4.2.3 Status Display	4-4
4.2.4 Monitor Parameter Display	4-5

4.1 Axis Monitor

The axis monitor is a function to monitor the status of each axis in the "Axis Monitor" window.

The status (Ready, Enable, Alarm, Warning, Profile Complete, In Position, Motion Command) and other extended monitoring parameters can be monitored.

The axis monitor updates when displayed in the Main Window. Scrolling displays other axes and parameters which are out of the window.

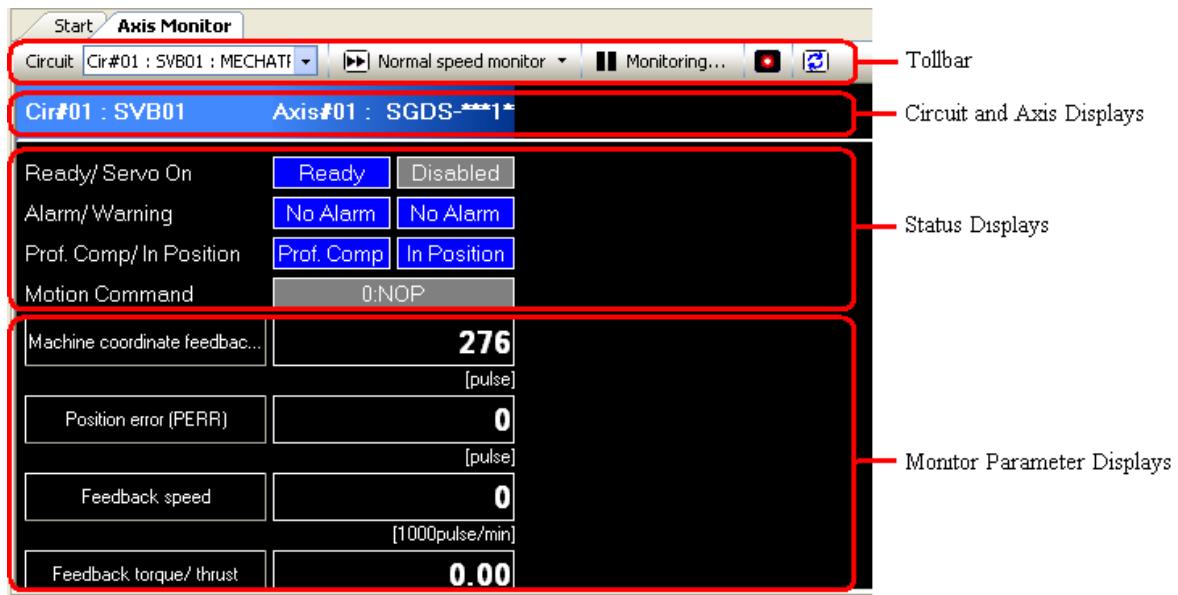
- ◆ The axes displayed:

SVB: The axes which are connected via MECHATROLINK.

SVA-01: 2 axes.

PO-01: 4 axes.

SVR: 16 axes.



4.2 Axis Monitor Display

The display of the Axis Monitor Window is described below.

4.2.1 Toolbar

Circuit ( Cir#01 : SVB01 : MECHAT)

Monitoring the selected circuit.

Monitor type ( High speed monitor /  Normal speed monitor /  Low speed monitor)

The update cycle can be chosen from "High Speed, Normal Speed, Low Speed".

Monitoring ( Monitoring... /  Monitoring...)

Click the button to select stop or start monitoring.

Alarm monitor ()

Click the button to display the Alarm Monitor window.

Refresh ()

Click the button to update the Axis Monitor window.

4.2.2 Circuit and Axis Display

(1) Circuit Display

The motion module number (SVB, SVA, PO-01, SVR) of the axis and module name are displayed.

(2) Axis Display

The axis name and the product type of axis are displayed.

4.2.3 Status Display

The status of the Ready, Enable, Alarm, Warning, Profile Complete, In Position and Motion Command are displayed.

(1) Ready, Enabled

The status is displayed.

Ready (**Not Ready** / **Ready**) : The status if the axis is ready to operate.

Enabled (**Disabled** / **Enabled**) : The status if the axis is enabled.

(2) Alarm, Warning

The status of the alarm and warning are displayed.

[Alarm, warning status]

No Alarm (**No Alarm**) : No alarm or warning.

Alarm (**Alarm**) : Alarm has occurred.

Warning (**Warning**) : Warning has occurred.

Clicking the "status" displays the Alarm Warning Dialog Box. Details of the alarm and warning are displayed. Refer to "Chapter 5: Alarm Monitor" for more information on the Alarm/Warning monitoring function.

(3) Profile Complete, In Position

The status of Profile Complete and In Position are displayed. When Profile Complete or In Position signal is ON, the lamp is displayed in blue.

Profile Complete (**Prof. Comp** / **Prof. Comp**) : The status of the Profile Complete.

In Position (**In Position** / **In Position**) : The status of the In Position.

(4) Motion Command

The status of the motion command response code is displayed. The background is displayed in blue except "---" (NOP).

4.2.4 Monitor Parameter Display

The monitor parameters are displayed. The displayed parameters are chosen by selecting from the list or inputting the register number (Only I/O).

In default, Machine coordinate feedback position (APOS), Position error (PERR), Feedback speed, and Feedback torque/ thrust are displayed. Eight parameters can be displayed at the same time.

The selection of displayed parameters is saved in the project file. Therefore, when opening the Axis Monitor window again, the same parameters will be displayed.

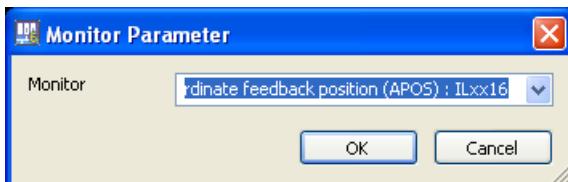
Machine coordinate feedback position (APOS)	5	6
	[pulse]	[pulse]
Position error (PERR)	1	0
	[pulse]	[pulse]
Feedback speed	-6	0
	[1000pulse/min]	[1000pulse/min]
Feedback torque/ thrust	-0.04	-0.04
	[%]	[%]
Parameter...	-----	-----
	[...]	[...]

(1) Monitoring the Monitor Parameters

- Click the Monitor Parameter button ().

The Monitor Parameter Dialog Box is displayed.

- Select a parameter from the combo box or input a register number (Only I/O) directly.



Monitor parameters which are selectable from the combo box

Monitor Parameter	Register	Unit
Machine coordinate target position (TPOS)	ILxx0E	Reference unit
Target position (CPOS)	ILxx10	Reference unit
Machine coordinate system position (MPOS)	ILxx12	Reference unit
Machine coordinate feedback position (APOS)	ILxx16	Reference unit
Machine coordinate latch position (LPOS)	ILxx18	Reference unit
Position error (PERR)	ILxx1A	Reference unit
POSMAX number of turns	ILxx1E	[rev]
Speed reference output monitor	ILxx20	[pulse/sec]
Feedback speed	ILxx40	Speed unit selection
Feedback torque/ thrust	ILxx42	Torque unit selection

- Click the OK button.

The monitor parameters are displayed.

Chapter 5

Alarm Monitor

This chapter describes how to use the Alarm Monitor.

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5.1.1 Alarm Monitor Display.....	5-3
5.1.2 When Alarm, Warning Occurs	5-4

5.1 Alarm Monitor

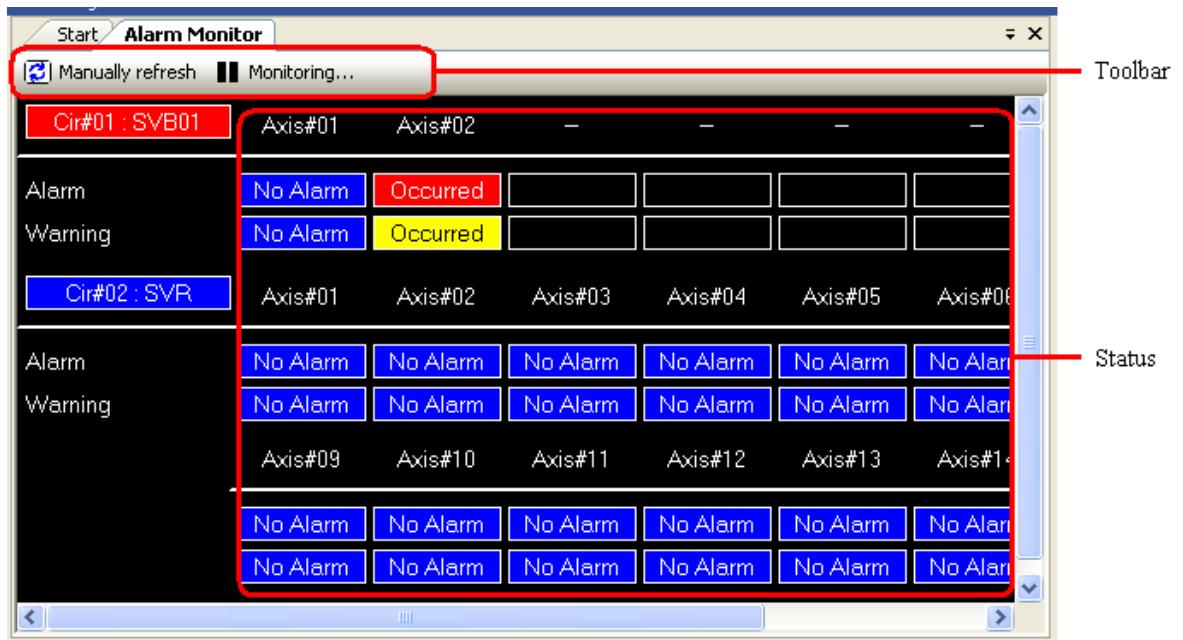
The Alarm Monitor window displays the alarm information of all axes in one window. The status of alarm, warning and alarm code are displayed.

When an alarm or warning occurs, status is displayed as **Occurred** or **Occurred**. When no alarm or warning occurs, it is displayed as **No Alarm**.

Clicking "status" displays the Alarm Warning Dialog Box. As a result, detailed information of the alarm and warning can be confirmed.

- ◆ All the monitor data displays by “----” when off-line.

The status and alarm code are displayed in each circuit number. The Alarm Monitor can display the information of up to eight axes horizontally.



5.1.1 Alarm Monitor Display

(1) Toolbar

In the toolbar, there are two icons to refresh manually and start/stop monitoring.

Manually refresh ( Manually refresh)

Alarm and warning information in the Alarm Monitor window is updated manually.

- ◆ The Alarm Monitor Window is not refreshed automatically.

Monitoring ( Monitoring... /  Monitoring...)

Click the button to stop or start the monitoring.

(2) Status

When an alarm or warning occurs, the status of the alarm or warning is displayed as shown below.

Alarm ( Occurred) : Alarm is occurring.

Warning ( Occurred) : Warning is occurring.

No Alarm ( No Alarm) : No alarm or warning.

(3) Show, Hide the Circuit

The monitoring data of each circuit can be shown or hidden by clicking the circuit number. As a result, only selected axes can be displayed.

i.e. Show

Cir#01 : SVB01	Axis#01	Axis#02	Axis#03	Axis#04	-	-
Alarm	 No Alarm	 No Alarm	 No Alarm	 No Alarm		
Warning	 No Alarm	 No Alarm	 No Alarm	 No Alarm		

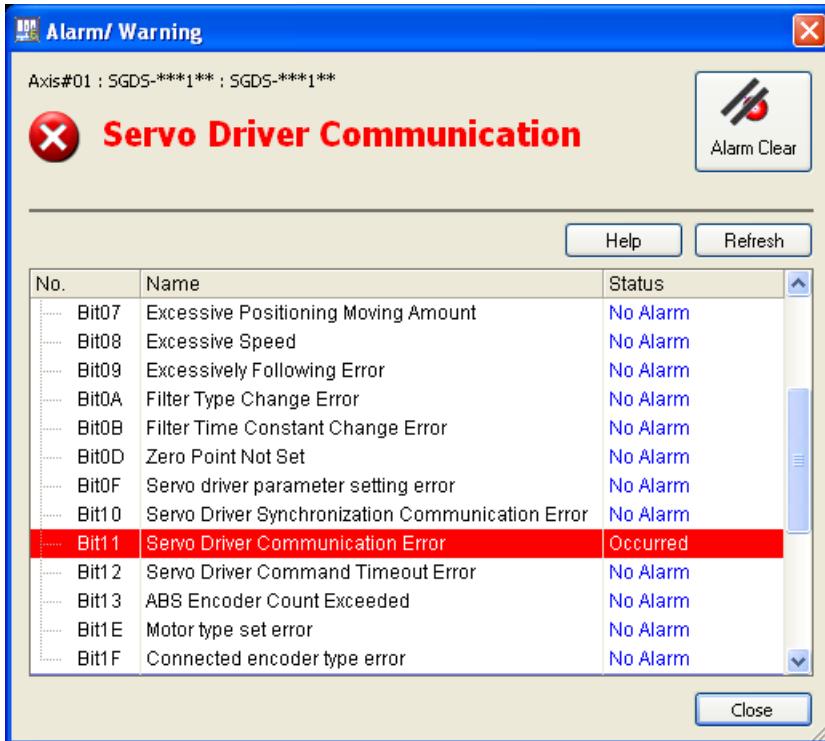
i.e. Hide



5.1.2 When Alarm, Warning Occurs

Click the status in the Alarm Monitor window. The Alarm/ Warning Dialog Box is displayed.

Clicking the "Help" button displays detailed information of the alarm or warning. Correct the alarm by checking "help". Then click the Alarm Clear button to reset the alarm.



Axis name (Axis#01 : SGDS-***1** : SGDS-***1**)

"Axis number", "comment" and "product type" are displayed in order.

Alarm, warning name (**Servo Driver Communication**)

The Alarm or Warning name is displayed.



To clear the alarm.

Help (**Help**)

The description of the occurring alarm in the manual "Machine Controller MP2200/MP2300 Motion Module User's Manual" is displayed.

Refresh (**Refresh**)

To update the Alarm, Warning Dialog Box.

No.	Name	Status
- IL8004	Alarm	0x00020000
	Bit00	No Alarm
	Bit01	No Alarm
	Bit02	No Alarm
	Bit03	No Alarm

The BIT number, the parameter name, and the status are displayed.

Close (**Close**)

To close the Alarm, Warning Dialog Box.

(1) Alarm, Warning Information

All alarms and warnings are displayed in the Alarm, Warning display Dialog Box.

Chapter 6

Additional Function of Compile Options

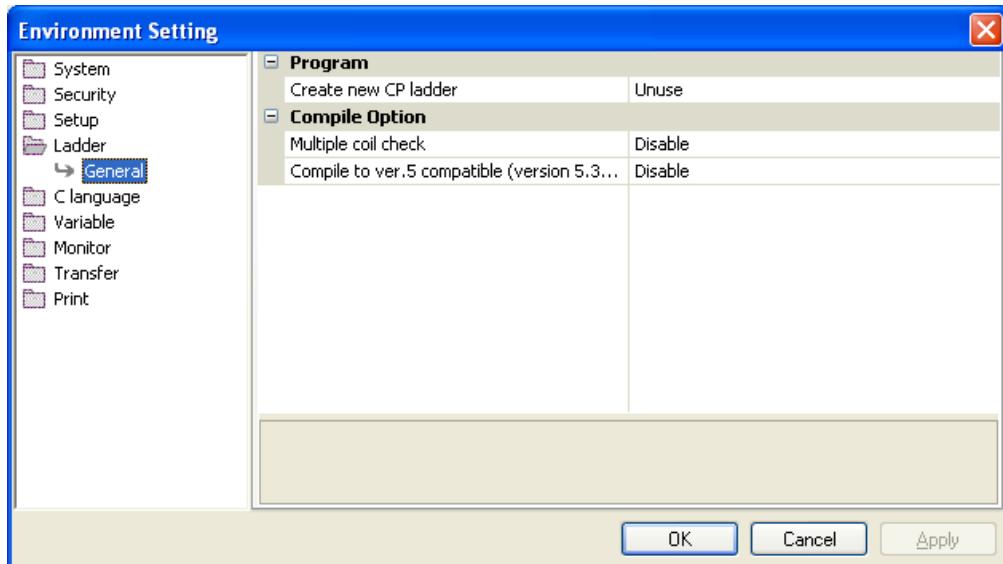
This chapter describes an additional function of compile options.

6.1 Additional Function of Compile Options	6-2
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6.1 Additional Function of Compile Options

The ladder program "Compile Options" can be set without displaying the ladder program in this version or later.

Select "Ladder" – "General" from the tree in the Environment Setting Dialog Box and the Compile Option settings are displayed.



Program

Create new CP ladder

When "Use" is selected, "Create new CP ladder" is displayed in Ladder Sub-window popup menus.

Compile Option

The option for compiling the ladder program is selected. The Compile Option can be set without displaying the ladder program.

Enable Multiple Coil Check:

When "Enable" is selected, duplicate coils in the target program are checked during the compile.

Compile to Ver.5 Compatible:

When "Enable" is selected, ladder programs compiled with MPE720 version 6 can be displayed and edited with MPE720 version 5 (Version 5.34 or later).

Chapter 7

Troubleshooting

This chapter describes how to use the System Monitor function to find errors in the program.

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7.3 Error Codes	7-11

7.1 Troubleshooting

Troubleshooting is a function to analyze problems such as the error, battery alarm, scan time etc.

When an error occurs, the message referencing the error is displayed in the System Monitor Sub-window.

Click the message "The alarm occurred. Please click with the mouse and execute the troubleshooting" to begin the troubleshooting.

It is possible to analyze the error in the ladder program, motion program and sequence program.

Also, an I/O module error can be detected. There are two types of I/O errors.

- **Station Error**

This type of error occurs when the controller cannot communicate with network I/O because of the disconnection of wiring or protocol differences.

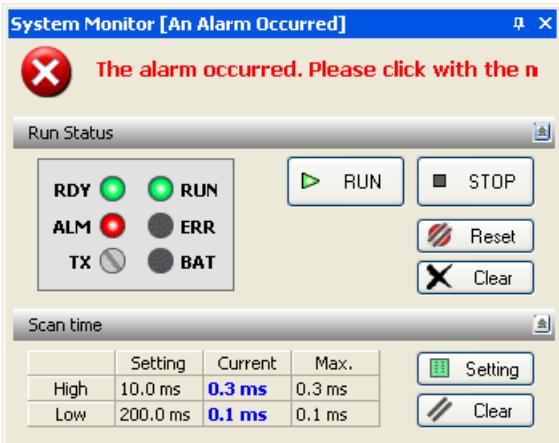
- **I/O Error**

i.e. The I/O module has a blown fuse.

7.2 Troubleshooting Flow

7.2.1 Start Troubleshooting

- When an error occurs, the System Monitor Sub-window automatically appears and the alarm is displayed in the status area.



- The System Monitor can be configured in the Environment Setting Dialog Box. Refer to "(2) Pop-up Display When an Error Is Detected" in "MPE720 Version 6 User's Manual 6.2.5 System Monitor" for more information.
- Click the message, "The alarm occurred. Please click with the mouse and execute the troubleshooting."
 - The error message describing the alarm is displayed.
 - The details of the error message and the operation method for troubleshooting after step 3 are different depending on the type of the error.
 - Operation error; refer to "7.2.2 (1) An operation error occurs in the program".
 - I/O error; refer to "7.2.2 (2) I/O error occur".

7.2.2 Troubleshooting Details

The way to analyze a problem is different depending on the type of error: ladder program, motion program, sequence program, or I/O error.

When an operation error occurs, refer to "(1) An operation error occurs in the program". When an I/O error occurs, refer to "(2) I/O error occurs".

(1) An operation error occurs in the program

The way to analyze an operation error occurring in the ladder program, motion program, or sequence program is described.

The analysis procedure is different according to where the error occurs. (The following example is the case if the error occurs in the ladder program.)

- [case a] The operation error occurs in the program (except functions).
 - [case b] The operation error occurs in the function which is called from a program (except functions).
 - [case c] The operation error occurs in a function which is called from another function.
 - [case d] The operation error occurs in an uncertain program.
- ◆ Error information is not cleared even if the cause displayed in the System Monitor Sub-window is corrected when multiple operation errors occur at the same time. In this case, error information might be incorrect. Please clear last error information by clicking the Reset button.

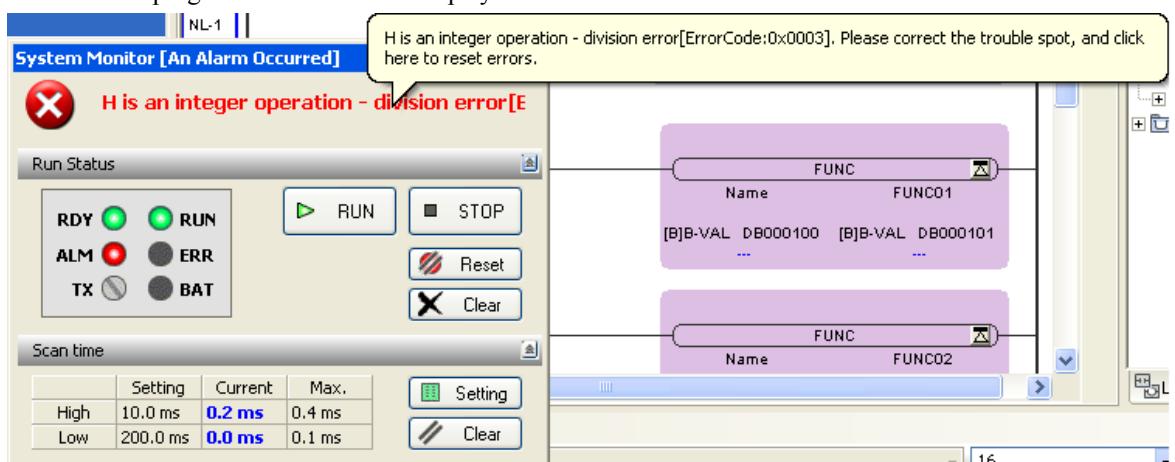
[case a] The operation error occurs in the program (except functions).

1. The following error message is displayed.



2. Confirm the error message. Then click OK button.

The name of the program with the error is displayed.



- ◆ A pop-up is displayed when the mouse is held over the status. Error information can be confirmed at a glance.

3. Correct the problem.

4. Compile the ladder program. Save the motion program or the sequence program.

[case b] The operation error occurs in the function which is called from a program (except functions).

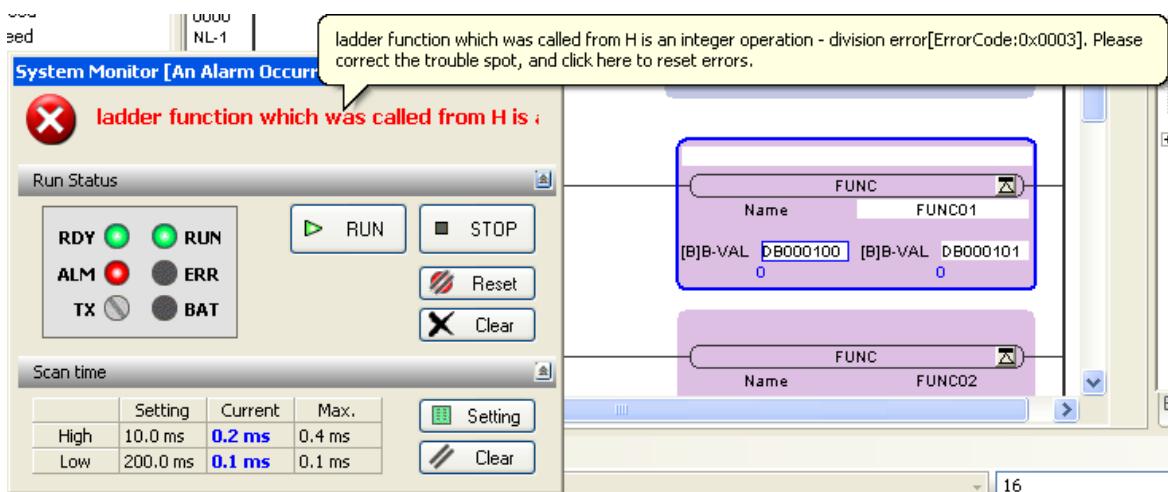
1. The following error message is displayed.



2. Confirm the error message. Then click OK.

The name of the program with the error is displayed.

The program name and step number which specify the instruction calling the function with the error are displayed in the System Monitor Sub-window.



◆ A pop-up is displayed when the mouse is held over the status. Error information can be confirmed at a glance.

3. Correct the problem.

4. Compile the ladder. Save the motion program or the sequence program.

[case c] The operation error occurs in a function which is called from another function.

1. The following error message is displayed.

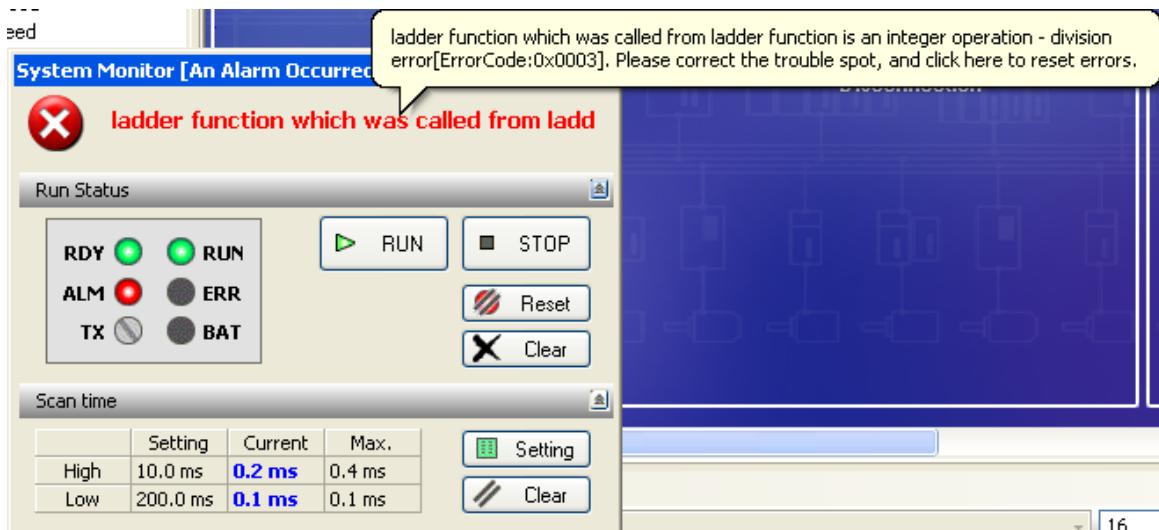


2. Confirm the error message. Then click OK.

Error information is displayed in the System Monitor Sub-window.

The program is not displayed because the location where the error occurs cannot be specified.

3. Find the function which is calling the function. Then find the FUNC instruction object in the program.



4. Display the function program which is called from the FUNC instruction object. Then correct the program.

Specify the type of instruction causing the error based on error information. Then find the instruction causing the error and correct program.

5. Compile the ladder program. Save the motion program or the sequence program.

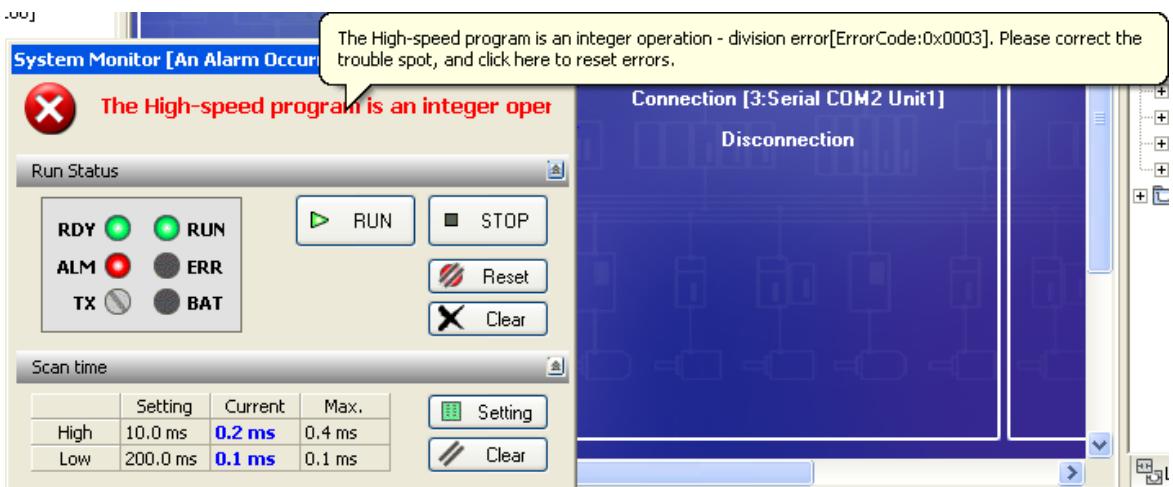
[case d] The operation error occurs in an uncertain program.

1. The following error message is displayed when MPE720 version 6 assesses that it is not the latest error information.
i.e. When the program which has been making the error is deleted, MPE720 Version 6 assesses as above.



2. Confirm the error message. Then click the OK Button.

Old error information may be displayed in the System Monitor Sub-window status.

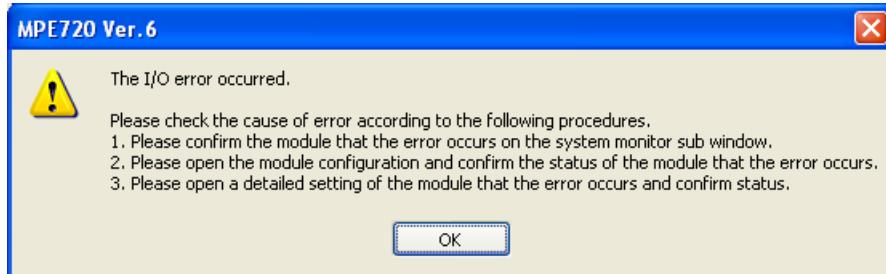


3. Click Status to clear the error information.

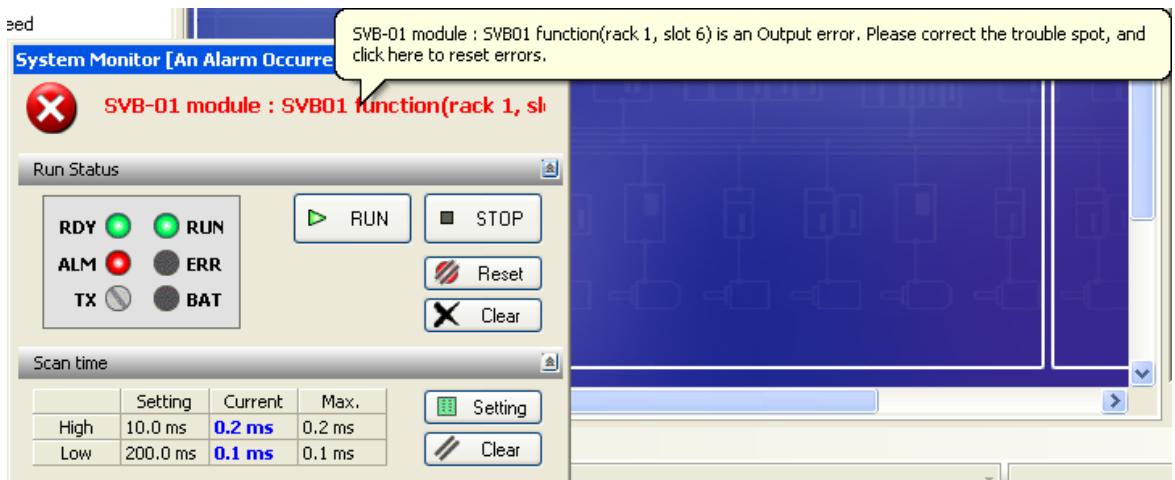
Error information will be updated.

(2) I/O error occurs

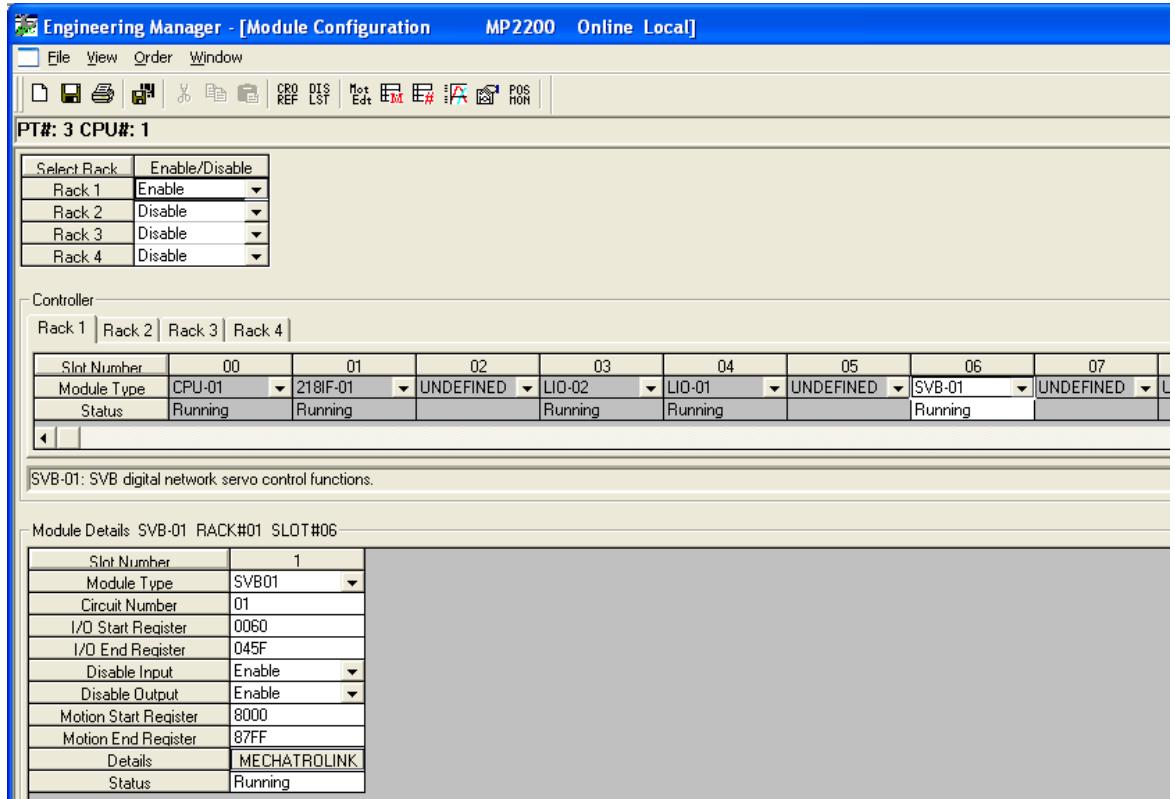
- When an error occurs on the I/O module mounted to the machine controller, the following error message is displayed.



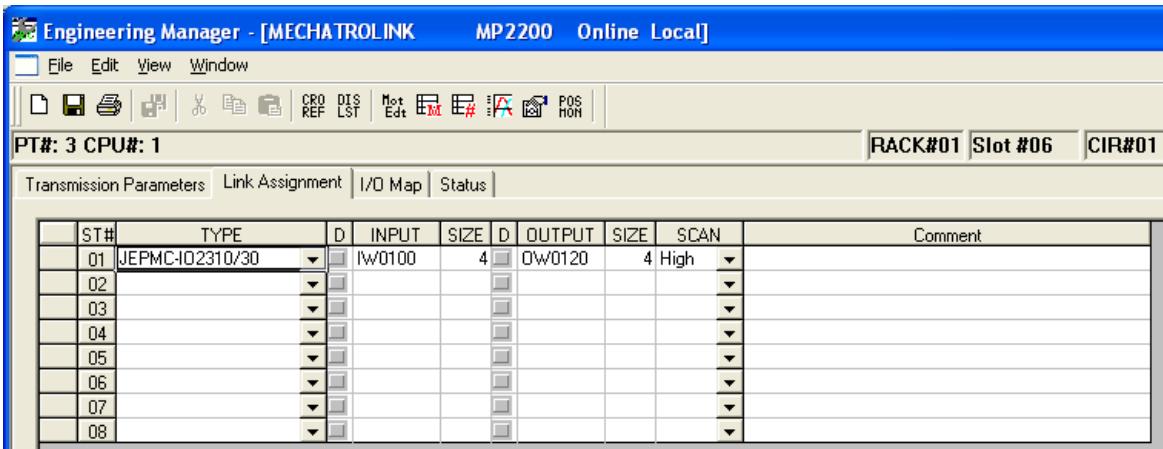
- Confirm the error message. Then click the OK button.



- Confirm the module information. Then display Module Configuration.

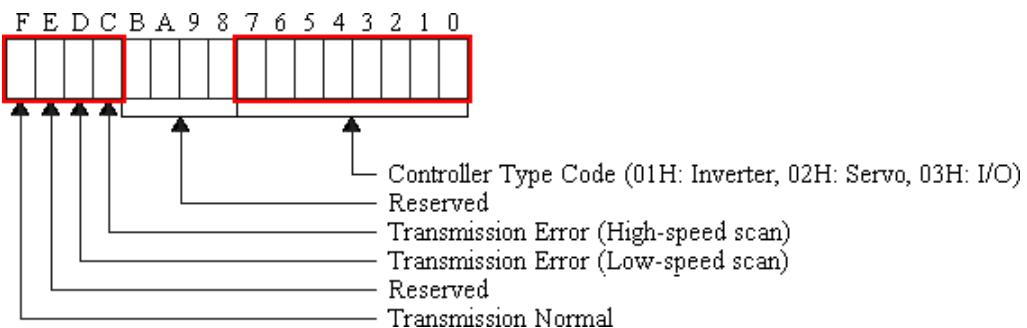


4. Display the Module Configuration with the I/O configuration that has an error.



The I/O which has generated an error is indicated on the status (STS) tab.

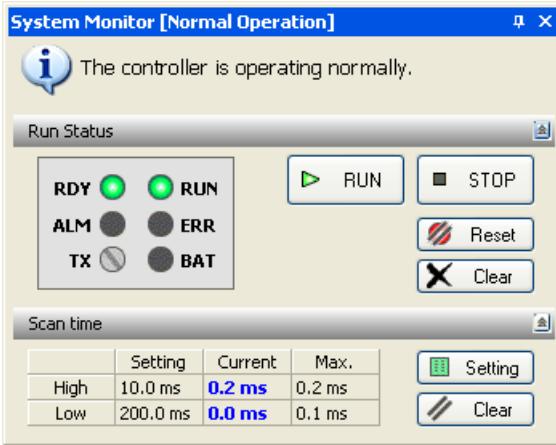
- ◆ Status is displayed as a hexadecimal number.



5. Save the Module Configuration.

7.2.3 Complete the Troubleshooting

When correction of the error is finished and no other errors occur, the System Monitor Sub-window displays normally.



- ◆ If the program is not modified correctly or another error remains, repeat the procedure "7.3 Error Codes" and analyze the error again.

7.3 Error Codes

The following table shows the error codes that can be detected by the System Monitor.

Error Code	Error Classification	Error Code	Error Classification
0x01	Integer operation: Underflow	0x70	LAG error
0x02	Integer operation: Overflow	0x71	LLAG error
0x03	Integer operation: Division error	0x72	FGN error
0x09	Double integer operation: Underflow	0x73	IFGN error
0x0A	Double integer operation: Overflow	0x74	LAU error
0x0B	Double integer operation: Division error	0x75	SLAU error
0x10	Integer storage: Non-numeric error	0x76	FGN error
0x11	Integer storage: Underflow	0x77	IFGN error
0x12	Integer storage: Overflow	0x7E	SLAU error
0x21	Real number storage: Underflow	0x80	BIN error
0x22	Real number storage: Overflow	0x81	BIN error
0x23	Real number operation: Division by zero	0x82	BCD error
0x30	Real number operation: Invalid operation	0x83	BCD error
0x31	Real number operation: Exponential underflow	0x84	PARITY error
0x32	Real number operation: Exponential overflow	0x85	PARITY error
0x33	Real number operation: Division error	0x86	SQRT error
0x34	Real number storage: Exponential underflow	0x87	SIN error
0x35	Real number operation: Stack error	0x88	COS error
0x40	SQRT error	0x89	ATAN error
0x41	SIN error	0x8A	IN error
0x42	COS error	0x8B	OUT error
0x43	TAN error	0x8C	INR error
0x44	ASIN error	0x8D	OUTR error
0x45	ACOS error	0x8E	INS error
0x46	ATAN error	0x8F	OUTS error
0x47	EXP error	0x90	ROTL error
0x48	LN error	0x91	ROTR error
0x49	LOG error	0x92	MOVB error
0x4A	DZA error	0x93	MOVW error
0x4B	DZB error	0x94	SETW error
0x4C	LIMIT error	0x95	XCHG error
0x4D	PI error	0x96	LIMIT error
0x4E	PD error	0x97	LIMIT error
0x4F	PID error	0x98	DZA error
0x50	LAG error	0x99	DZA error
0x51	LLAG error	0x9A	DZB error
0x52	FGN error	0x9B	DZB error
0x53	IFGN error	0x9C	PWM error
0x54	LAU error	0x9D	SFC error
0x55	SLAU error	0x9E	SHFTL error
0x56	REM error	0x9F	SHFTR error
0x57	RCHK error	0xA0	BEXTD error
0x58	BSRCH error	0xA1	BPRESS error
0x59	SORT error	0xA2	SORT error
0x6D	PI error	0xA3	QSORT error
0x6E	PD error	0xA4	SORT error
0x6F	PID error	0xA5	QSORT error

Error Code	Error Classification
0xA6	RCHK error
0xA7	RCHK error
0xA8	COPYW error
0xA9	ASCII error
0xAA	BINASC error
0xAB	ASCBIN error
0xAC	BRCH error
0xAD	BSRCH error
0xAE	TMADD error
0xAF	TMSUB error
0xB1	SPEND error
0xC0	TBLBR error
0xC1	TBLBW error
0xC2	TBLSRL error
0xC3	TBLSRC error
0xC4	TBLCL error
0xC5	TBLMV error
0xC6	QTBLR error
0xC7	QTBLRI error
0xC8	QTBLW error
0xC9	QTBLWI error
0xCA	QTBLCL error
0xE0	MSEE error

Chapter 8

Communications Setting

This chapter describes the communication setting to connect MPE720 version 6 to the Machine Controller.

8.1 Communication Setting	8-2
8.2 Connect Using Ethernet	8-2
8.2.1 Computer Setting.....	8-2
8.2.2 Ethernet Port Setting	8-5
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8.1 Communication Setting

The following communication port can be used to connect.

- Ethernet (10 MB Ethernet, 100 MB Ethernet)
- Serial
- MP2100 BUS
- USB

8.2 Connect Using Ethernet

The following setting is necessary for communication using an Ethernet connection via CP-218 communications port on the 218IF-01 Module or 218IFA/B Module. There are two types of Ethernet communication hardware: the 218IF-01 Module (10 MB Ethernet) and the 218IFA/B Module(100 MB Ethernet).

8.2.1 Computer Setting

(1) Setting the IP Address

The IP address of the computer must be set before setting the Ethernet connection. The following description shows how to set the IP address.

1. Click the Start button. Then select “Settings” – “Control Panel” from the “Start Menu”.

Click the “Internet Options” icon in “Control Panel”.

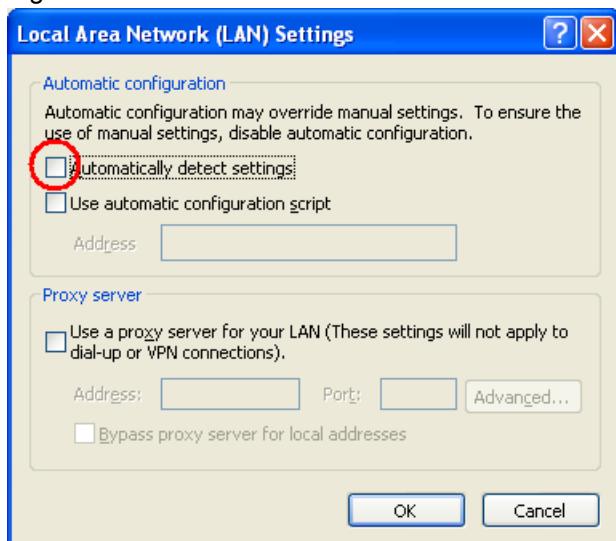
The Internet Properties Dialog Box is displayed.

2. Select the Connections Tab. Then click the LAN Settings button.

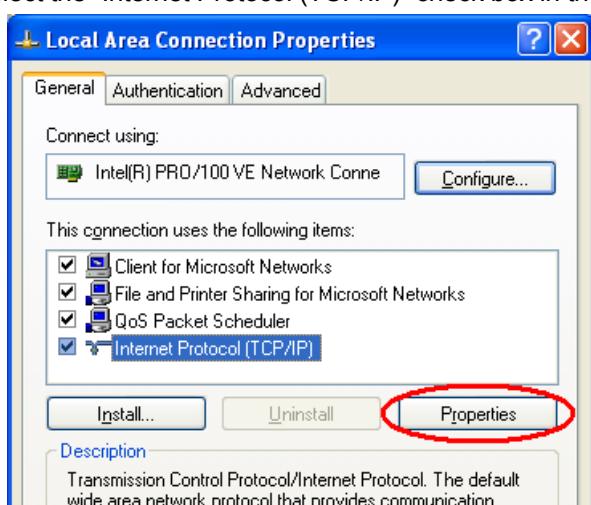


The "Local Area Network (LAN) Settings" Dialog Box is displayed.

3. Confirm that the “Automatically detect settings” check box is not selected. Then click OK to close the dialog box.

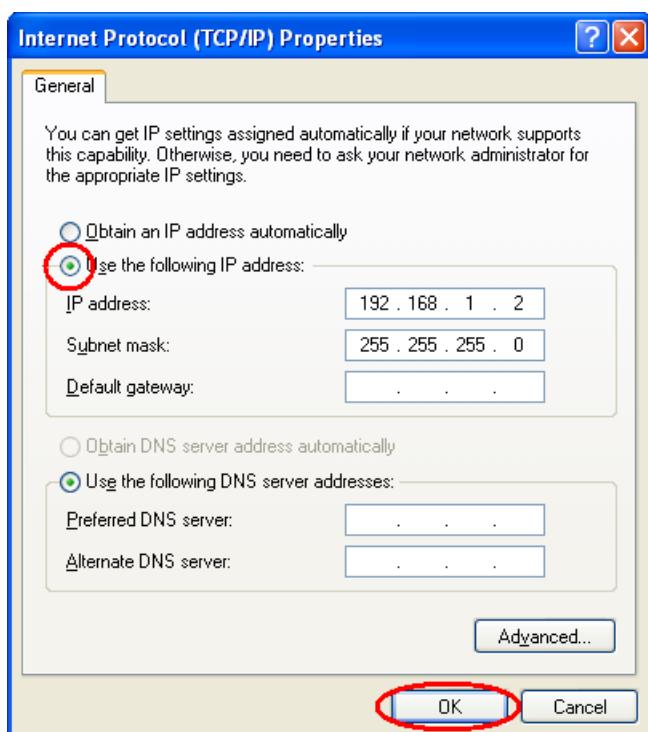


4. For Windows XP, click the Start button and select “Settings” – “Control Panel”. Then click the “Network Connections” Icon in the “Control Panel”.
For Windows 2000, click the Start button and select “Settings” – “Control Panel”. Then click the “Network and Dial-up Connections” Icon in the “Control Panel”.
The “Network Connections window” on Windows XP or the “Network and Dial-up Connections window” on Windows 2000 is displayed.
5. For Windows XP, select “Local Area Connection”. Then click “Change settings of this connection” in the “Network Tasks” field.
For Windows 2000, double-click the “Local Area Connection” icon.
The “Local Area Connection Properties” Dialog Box is displayed.
6. Select the “Internet Protocol (TCP/IP)” check box in the “General” tab. Then click the Properties button.



The “Internet Properties (TCP/IP)” Dialog Box is displayed.

7. Select “Use the following IP address”. Then enter “192 168 1 2” for the “IP address” and “255 255 255 0” for the “Subnet mask”.



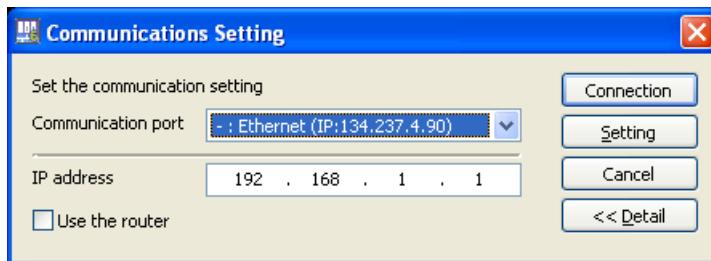
8. Click OK to close the dialog box.

8.2.2 Ethernet Port Setting

(1) How to Set an Ethernet Port

This section describes how to connect communications between a computer running MPE720 version 6 and a Machine Controller.

1. Select "Online" – "Communications Setting" from the "Main Menu" or click "Communications Setting" under "Controller (or Project)" in the "Start Window".
The "Communications Setting Dialog Box" is displayed.
2. Select the logical port number to be used for connecting to the Machine Controller. Then click the Connection button.



The Communication Setting Dialog Box is closed and MPE720 version 6 is connected to the Machine Controller.

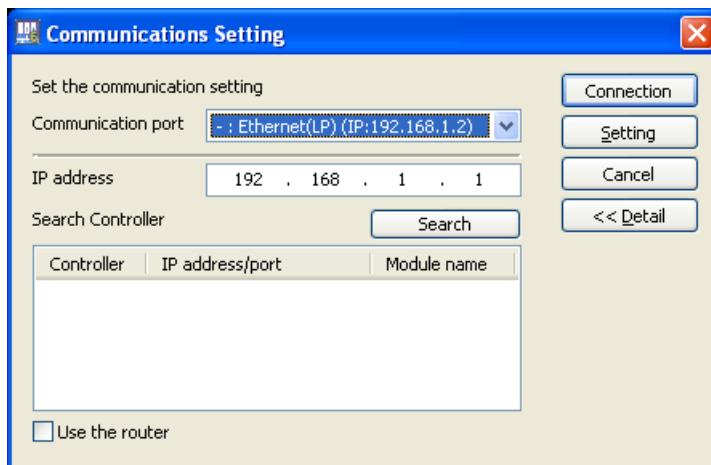
- ◆ The Connection button and the Setting button are invalid while connected to the Machine Controller and communication settings cannot be changed.

(2) How to Set an Ethernet (LP) Port

When Ethernet (LP) is selected, the "Search Controller" is displayed. When the Search button is clicked, MPE720 version 6 searches the machine controller connected via Ethernet (LP) and the result is displayed in the list.

When the Machine Controller is selected from "Search Controller", IP address of the Machine Controller is set to the IP address column automatically.

1. Select "Online" – "Communications Setting" from the "Main Menu" or click "Communications Setting" under "Controller (or Project)" in the Start window.
The Communications Setting Dialog Box is displayed.
2. Select the logical port number to be used for connecting to the Machine Controller. Then click the Setting button.



3. Click the Connection button.

The Communications Setting Dialog Box is closed and MPE720 version 6 is connected to the Machine Controller.

- ◆ The Connection button and the Setting button are invalid while connected to the Machine Controller, and communication settings cannot be changed.

Confirm IP address by the following method when MPE720 cannot connect to the machine controller.

- Setting the Communication Port

1. Display the "Communication Setting" Dialog Box. Then click the Search button.
2. Machine controller name and IP address are displayed in the "Search Controller".
3. Verify the IP address which is searched and input to IP address column. Then click the Connection button.

- Setting the Ethernet Port

Confirm if the port setting of the computer is correct. Refer to "(1) Setting the IP Address".

8.3 Connect Using Serial Port

8.3.1 Serial Port Settings

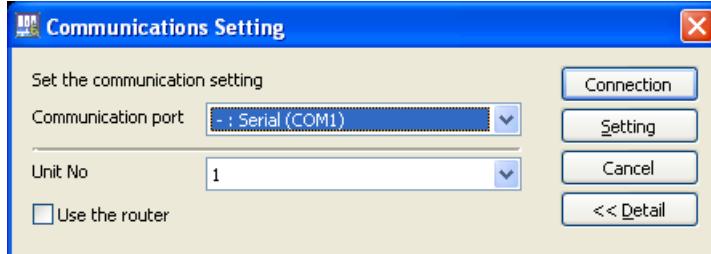
(1) Setting of Serial Port

This section describes the setting to connect to the Machine Controller using the serial port.

1. Select “Online” – “Communications Setting” from the Main Menu or click “Communications Setting” under “Controller (or Project)” in the Start window.

The Communications Setting Dialog Box is displayed.

2. Select the logical port number to be used for connecting to the Machine Controller. Then click the Setting button.



The Communications Setting Dialog Box is closed and MPE720 version 6 is connected to the Machine Controller.

- ◆ The Connection button and the Setting button are invalid while connected to the Machine Controller and communication settings cannot be changed.